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# A differential–difference system related to toroidal Lie algebra

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## Abstract

We present a novel differential–difference system in  $(2+1)$ -dimensional space–time (one discrete, two continuum), arising from Bogoyavlensky’s  $(2+1)$ -dimensional Korteweg–de Vries hierarchy. Our method is based on the bilinear identity of the hierarchy, which is related to the vertex-operator representation of the toroidal Lie algebra,  $\mathfrak{sl}_2^{\text{tor}}$ .

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## 1. Introduction and main results

Multi-dimensional generalization of classical soliton equations is one of the most exciting topics in the field of integrable systems. Among other things, Calogero [1] proposed an interesting example that is a  $(2+1)$ -dimensional extension of the Korteweg–de Vries (KdV) equation

$$u_t = \frac{1}{4}u_{xxy} + uu_y + \frac{1}{2}u_x \int^x u_y dx. \quad (1)$$

Yu *et al* [2] obtained multi-soliton solutions of the  $(2+1)$ -dimensional KdV equation (1) using Hirota’s bilinear method. Let us consider the following Hirota-type equations:

$$(D_x^4 - 4D_x D_{t'})\tau \cdot \tau = 0 \quad (2)$$

$$(D_y D_x^3 + 2D_y D_{t'} - 6D_t D_x)\tau \cdot \tau = 0 \quad (3)$$

where we have used the  $D$ -operators of Hirota defined as

$$D_x D_y \dots f(x, y, \dots) \cdot g(x, y, \dots) \stackrel{\text{def}}{=} \partial_s \partial_t f(x+s, y+t, \dots) g(x-s, y-t, \dots)|_{s,t,\dots=0}.$$

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Note that we have introduced the auxiliary variable  $t'$  that is a hidden parameter in (1). If we set  $u = 2(\log \tau)_{,xx}$  and use (2) to eliminate  $\partial_{t'}$ , then one can show that  $u = u(x, y, t)$  solves (1).

Bogoyavlensky [3] showed that there is a hierarchy of higher-order integrable equations associated with (1). In [4], Ikeda and Takasaki generalized Bogoyavlensky's hierarchy from the viewpoint of Sato's theory of KP hierarchy [5–8], and discussed the relationship to toroidal Lie algebras. We note that the relation between integrable hierarchy and toroidal algebras was also discussed by Billig [9] and Iohara *et al* [10] using vertex-operator representations.

In the present paper, we propose the following differential–difference system with the same symmetry:

$$\partial_t u_k = \Delta_{-k} \left( \frac{\partial_x u_{k+1}}{1 - \exp(-u_{k+1} - u_k)} - \frac{\partial_x u_k}{1 - \exp(u_{k+1} + u_k)} - \frac{1 + \exp(u_{k+1} + u_k)}{1 - \exp(u_{k+1} + u_k)} v_k \right) \tag{4}$$

$$\Delta_{-k} v_k = \frac{\partial_x u_{k+1}}{u_{k+1}} + \frac{\partial_x(u_{k+1} + u_k)}{1 - \exp(u_{k+1} + u_k)} + \frac{\partial_x u_k}{u_k} + \frac{\partial_x(u_k + u_{k-1})}{1 - \exp(u_k + u_{k-1})} \tag{5}$$

where  $\Delta_{-k}$  denotes the backward-difference operator  $\Delta_{-k} \stackrel{\text{def}}{=} 1 - \exp(-\partial_k)$  ( $\Delta_{-k} u_k = u_k - u_{k-1}$ ). We also show that this system has soliton-type solutions.

### 2. Lie algebraic derivation of the bilinear identity

Here we briefly review the Lie algebraic derivation of the bilinear identity of Bogoyavlensky's hierarchy [4], which is a generating function of Hirota-type differential equations. We remark that the Lie algebra considered in [4] is bigger than that considered in this paper. We have not included the derivations to  $\mathfrak{sl}_2^{\text{tor}}$  here, since these are not needed for our purpose. Due to this difference, the proof given below may be simpler than that of [4].

The two-toroidal Lie algebra  $\mathfrak{sl}_2^{\text{tor}}$  [11, 12] is the universal central extension of the double-loop algebra  $\mathfrak{sl}_2 \otimes \mathbb{C}[s, s^{-1}, t, t^{-1}]$ , while the affine Lie algebra  $\widehat{\mathfrak{sl}}_2$  is the central extension of  $\mathfrak{sl}_2 \otimes \mathbb{C}[t, t^{-1}]$ . Let  $A$  be the ring of Laurent polynomials of two variables  $s$  and  $t$ . As a vector space,  $\mathfrak{sl}_2^{\text{tor}}$  is isomorphic to  $\mathfrak{sl}_2 \otimes \mathbb{C}[s, s^{-1}, t, t^{-1}] \oplus \Omega_A/dA$ , where  $\Omega_A$  denotes the module of Kähler differentials of  $A$  defined with the canonical derivation  $d : A \rightarrow \Omega_A$ . We define the Lie algebra structure of  $\mathfrak{sl}_2^{\text{tor}}$  by

$$[x \otimes a, y \otimes b] = [x, y] \otimes ab + (x|y) \overline{(da)b} \quad (x, y \in \mathfrak{sl}_2, a, b \in A) \tag{6}$$

$$[\mathfrak{sl}_2^{\text{tor}}, \Omega_A/dA] = 0 \tag{7}$$

where  $(x|y)$  denotes the Killing form and  $\overline{\cdot} : \Omega_A \rightarrow \Omega_A/dA$  the canonical projection.

In terms of the generating series  $X_m(z)$  ( $X = E, F, H, m \in \mathbb{Z}$ ),  $K_m^s(z)$  and  $K_m^t(z)$ , defined by

$$X_m(z) \stackrel{\text{def}}{=} \sum_{n \in \mathbb{Z}} X \otimes s^n t^m \cdot z^{-n-1}$$

$$K_m^s(z) \stackrel{\text{def}}{=} \sum_{n \in \mathbb{Z}} \overline{s^n t^m d \log s} \cdot z^{-n}$$

$$K_m^t(z) \stackrel{\text{def}}{=} \sum_{n \in \mathbb{Z}} \overline{s^n t^m d \log t} \cdot z^{-n-1}$$

the relation (6) can be expressed as

$$X_n(z)Y_n(w) = \frac{1}{z-w} [X, Y]_{m+n}(w) + \frac{1}{(z-w)^2} (X|Y) K_{m+n}^s(w) + \frac{m}{z-w} (X|Y) K_{m+n}^t(w) + \text{regular as } z \rightarrow w. \tag{8}$$

There exists a class of representations of  $\mathfrak{sl}_2^{\text{tor}}$ , which comes directly from that of  $\widehat{\mathfrak{sl}}_2$ . We consider the space of polynomials

$$F_y \stackrel{\text{def}}{=} \mathbb{C}[y_j, j \in \mathbb{Z}] \otimes \mathbb{C}[\exp(\pm y_0)]$$

and define the generating series  $\varphi(z)$  and  $V_m(y; z)$  by

$$\varphi(z) \stackrel{\text{def}}{=} \sum_{n \in \mathbb{Z}} n y_n z^{n-1} \quad V_m(y; z) \stackrel{\text{def}}{=} \exp \left[ m \sum_{n \in \mathbb{Z}} y_n z^n \right].$$

**Proposition 1 (cf [10, 13]).** *Let  $(V, \pi)$  be a representation of  $\widehat{\mathfrak{sl}}_2$  such that  $\overline{d \log s} \mapsto c \cdot \text{id}_V$  for  $c \in \mathbb{C}$ . Then we can define the representation  $\pi^{\text{tor}}$  of  $\mathfrak{sl}_2^{\text{tor}}$  on  $V \otimes F_y$  such that*

$$\begin{aligned} X_m(z) &\mapsto X^\pi(z) \otimes V_m(z) \\ K_m^s(z) &\mapsto c \cdot \text{id}_V \otimes V_m(z) \\ K_m^t(z) &\mapsto c \cdot \text{id}_V \otimes \varphi(z) V_m(z) \end{aligned}$$

where  $X = E, F, H, m \in \mathbb{Z}$  and  $X^\pi(z) \stackrel{\text{def}}{=} \sum_{n \in \mathbb{Z}} \pi(X \otimes s^n) z^{-n-1}$ .

**Proof.** Using the operator-product expansion for  $\widehat{\mathfrak{sl}}_2$

$$X(z)Y(w) = \frac{1}{z-w} [X, Y](w) + \frac{1}{(z-w)^2} (X|Y)K + \text{regular as } z \rightarrow w$$

and the property  $V_m(z)V_n(z) = V_{m+n}(z)$ , it is straightforward to show that  $X_m(z)$  satisfies (8). The remaining relations can be checked by direct calculations.  $\square$

To see the relationship to soliton theory, we shall consider the representation of  $\widehat{\mathfrak{sl}}_2$  on the fermionic Fock space [7, 8]. Let  $\psi_j, \psi_j^* (j \in \mathbb{Z})$  be free fermions with the canonical anti-commutation relation. In terms of the generating series defined as

$$\psi(\lambda) = \sum_{n \in \mathbb{Z}} \psi_n \lambda^n \quad \psi^*(\lambda) = \sum_{n \in \mathbb{Z}} \psi_n^* \lambda^{-n}$$

the canonical anti-commutation relation is written as

$$[\psi(\lambda), \psi^*(\mu)]_+ = \delta(\lambda/\mu) \quad [\psi(\lambda), \psi(\mu)]_+ = [\psi^*(\lambda), \psi^*(\mu)]_+ = 0 \quad (9)$$

where  $\delta(\lambda) \stackrel{\text{def}}{=} \sum_{n \in \mathbb{Z}} \lambda^n$  is the formal delta-function.

Consider the fermionic Fock space  $\mathcal{F}$  with the vacuum vector  $|\text{vac}\rangle$  satisfying

$$\begin{aligned} \psi_j |\text{vac}\rangle &= 0 & \text{for } j < 0 \\ \psi_j^* |\text{vac}\rangle &= 0 & \text{for } j \geq 0 \end{aligned}$$

and the dual Fock space  $\mathcal{F}^*$  with the dual vacuum vector  $\langle \text{vac} |$  satisfying

$$\begin{aligned} \langle \text{vac} | \psi_j &= 0 & \text{for } j \geq 0 \\ \langle \text{vac} | \psi_j^* &= 0 & \text{for } j < 0 \\ \langle \text{vac} | \text{vac} \rangle &= 1. \end{aligned}$$

As mentioned in [7, 8], a level-1 representation of  $\widehat{\mathfrak{sl}}_2$  is given by the elements

$$:\psi(\lambda)\psi^*(-\lambda): = \sum_{j, n \in \mathbb{Z}} (-1)^j : \psi_{j+n} \psi_j^* : \lambda^n$$

where  $:\cdot:$  denotes the fermionic normal ordering,  $:\psi_i \psi_j^* : \stackrel{\text{def}}{=} \psi_i \psi_j^* - \langle \text{vac} | \psi_i \psi_j^* | \text{vac} \rangle$ . Applying proposition 1, we can construct a representation of  $\mathfrak{sl}_2^{\text{tor}}$  on the space  $\mathcal{F}_y \stackrel{\text{def}}{=} \mathcal{F} \otimes F_y$  with the vacuum vector  $|\text{vac}\rangle^{\text{tor}} \stackrel{\text{def}}{=} |\text{vac}\rangle \otimes 1$ .

We now introduce the following operator acting on  $\mathcal{F}_y \otimes \mathcal{F}_{y'}$ :

$$\Omega^{\text{tor}} \stackrel{\text{def}}{=} \sum_{m \in \mathbb{Z}} \oint \frac{d\lambda}{2\pi i \lambda} \psi(\lambda) V_m(\lambda; y) \otimes \psi^*(\lambda) V_{-m}(\lambda; y').$$

Using the anti-commutation relation (9) and the relation  $V_m(y; \lambda) V_n(y; \lambda) = V_{m+n}(y; \lambda)$ , we can obtain the following identity by direct calculations:

$$[\Omega^{\text{tor}}, \psi(p)\psi^*(p)V_n(y; p) \otimes 1 + 1 \otimes \psi(p)\psi^*(p)V_n(y'; p)] = 0$$

which means the action of  $\mathfrak{sl}_2^{\text{tor}}$  on  $\mathcal{F}_y \otimes \mathcal{F}_{y'}$  commutes with  $\Omega^{\text{tor}}$ . It is then straightforward to show that

$$\Omega^{\text{tor}}(g|\text{vac}\rangle^{\text{tor}} \otimes g|\text{vac}\rangle^{\text{tor}}) = 0 \tag{10}$$

for  $g = \exp(X)$ ,  $X \in \mathfrak{sl}_2^{\text{tor}}$ .

To rewrite (10) into bosonic language, we have the following two lemmas.

**Lemma 1 ('Boson–fermion correspondence' [7, 8]).** *For any  $|v\rangle \in \mathcal{F}$ , we have the following formulae:*

$$\begin{aligned} \langle \text{vac} | \psi_0^* \exp(H(\mathbf{x})) \psi(\lambda) | v \rangle &= \exp(\xi(\mathbf{x}, \lambda)) \langle \text{vac} | \exp(H(\mathbf{x} - [\lambda^{-1}])) | v \rangle \\ \langle \text{vac} | \psi_{-1} \exp(H(\mathbf{x})) \psi^*(\lambda) | v \rangle &= \lambda \exp(-\xi(\mathbf{x}, \lambda)) \langle \text{vac} | \exp(H(\mathbf{x} + [\lambda^{-1}])) | v \rangle \end{aligned}$$

where we have used the following notation:

$$\begin{aligned} \mathbf{x} &= (x_1, x_3, \dots) \\ H(\mathbf{x}) &\stackrel{\text{def}}{=} \sum_{n=1}^{\infty} \sum_{j \in \mathbb{Z}} x_n \psi_j \psi_{n+j}^* \\ \xi(\mathbf{x}, \lambda) &\stackrel{\text{def}}{=} \sum_{n=1}^{\infty} x_n \lambda^n \\ [\lambda^{-1}] &\stackrel{\text{def}}{=} (1/\lambda, 1/2\lambda^2, 1/3\lambda^3, \dots). \end{aligned}$$

**Lemma 2 ([9, 10]).** *Let  $P(n) = \sum_{j \geq 0} n^j P_j$ , where  $P_j \in \text{Diff}(z)$  are differential operators that may not depend on  $z$ . If*

$$\sum_{n \in \mathbb{Z}} z^n P(n)g(z) = 0$$

for some formal series  $g(z) = \sum_j g_j z^j$ , then

$$P(\epsilon - z\partial_z)g(z)|_{z=1} = 0$$

as a polynomial in  $\epsilon$ .

Define the  $\tau$ -function as

$$\tau(\mathbf{x}, \mathbf{y}) \stackrel{\text{def}}{=} {}^{\text{tor}} \langle \text{vac} | \exp(H(\mathbf{x})) g | \text{vac} \rangle^{\text{tor}}.$$

From relation (10), together with lemma 1 and 2, we have the following bilinear identity:

$$\begin{aligned} \oint \frac{d\lambda}{2\pi i} \exp(\xi(\mathbf{x} - \mathbf{x}', \lambda)) \tau(\mathbf{x} - [\lambda^{-1}], y_0 + \eta(\check{\mathbf{b}}, \lambda^2), \check{\mathbf{y}} - \check{\mathbf{b}}) \\ \times \tau(\mathbf{x}' + [\lambda^{-1}], y_0 - \eta(\check{\mathbf{b}}, \lambda^2), \check{\mathbf{y}} + \check{\mathbf{b}}) = 0 \end{aligned} \tag{11}$$

where  $\check{\mathbf{y}} \stackrel{\text{def}}{=} (y_2, y_4, \dots)$  and  $\eta(\check{\mathbf{b}}, \lambda^2) \stackrel{\text{def}}{=} \sum_{n=1}^{\infty} b_{2n} \lambda^{2n}$ .

Expanding (11), we can obtain Hirota-type differential equations including (2) and (3) ( $x_1 = x, x_3 = t', y_0 = y, y_2 = t$ ). In this sense, the bilinear identity (11) is a generating function of Hirota-type differential equations of Bogoyavlensky’s hierarchy. The  $N$ -soliton solution of (11) is obtained as follows [4]:

$$\begin{aligned} \tau_N(\mathbf{x}, \mathbf{y}) &= \sum_{l=0}^N \sum_{j_1 < \dots < j_l} c_{j_1 \dots j_l} \prod_{m=1}^l a_{j_m} \exp(\eta_{j_m}(\mathbf{x}, \mathbf{y})) \\ \eta_j(\mathbf{x}, \mathbf{y}) &\stackrel{\text{def}}{=} \sum_{n=1}^{\infty} 2p_j^{2n-1} x_{2n-1} + \sum_{n=1}^{\infty} r_j p_j^{2n} y_{2n} \\ c_{j_1 \dots j_l} &\stackrel{\text{def}}{=} \prod_{1 \leq m < n \leq l} \frac{(p_{j_m} - p_{j_n})^2}{(p_{j_m} + p_{j_n})^2}. \end{aligned} \tag{12}$$

### 3. Derivation of the differential–difference system

We now apply the Miwa transformation [8, 14]

$$\begin{aligned} \mathbf{x}' &= l[\alpha] + m[\beta] + n[\gamma] \\ \mathbf{x} &= (l + 1)[\alpha] + (m + 1)[\beta] + (n + 1)[\gamma] \end{aligned} \tag{13}$$

to the bilinear identity (11). Here we have used the notation  $l[\alpha] = (l\alpha, l\alpha^2/2, l\alpha^3/3, \dots)$ . We first consider the case  $\mathbf{b} = (b_2, b_4, \dots) = \mathbf{0}$ . In this case, the bilinear identity (11) is reduced to that of the ordinary KP hierarchy. Thus we have the Hirota–Miwa equation (or the discrete KP equation)

$$\begin{aligned} \alpha(\beta - \gamma) \tau(l + 1, m, n; \mathbf{y}) \tau(l, m + 1, n + 1; \mathbf{y}) \\ + \beta(\gamma - \alpha) \tau(l, m + 1, n; \mathbf{y}) \tau(l + 1, m, n + 1; \mathbf{y}) \\ + \gamma(\alpha - \beta) \tau(l, m, n + 1; \mathbf{y}) \tau(l + 1, m + 1, n; \mathbf{y}) = 0 \end{aligned} \tag{14}$$

where  $\tau(l, m, n; \mathbf{y})$  denotes

$$\tau(l, m, n; \mathbf{y}) = \tau(\mathbf{x} = l[\alpha] + m[\beta] + n[\gamma], \mathbf{y}).$$

We then consider the time evolution with respect to  $y_0$  and  $y_2$ . Collecting the coefficients of  $b_2$  in the bilinear identity (11) gives

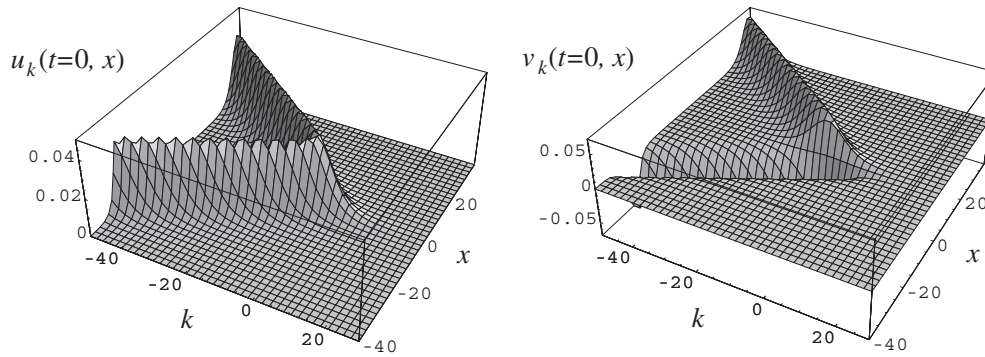
$$\oint \frac{d\lambda}{2\pi i} \exp(\xi(\mathbf{x} - \mathbf{x}', \lambda)) (D_{y_2} - \lambda^2 D_{y_0}) \tau(\mathbf{x}' + [\lambda^{-1}], \mathbf{y}) \cdot \tau(\mathbf{x} - [\lambda^{-1}], \mathbf{y}) = 0.$$

Applying the Miwa transformation (13) we obtain

$$\begin{aligned} \alpha^2 \beta \gamma (\beta - \gamma) D_{y_2} \tau(l + 1, m, n; \mathbf{y}) \cdot \tau(l, m + 1, n + 1; \mathbf{y}) \\ + \alpha \beta^2 \gamma (\gamma - \alpha) D_{y_2} \tau(l, m + 1, n; \mathbf{y}) \cdot \tau(l + 1, m, n + 1; \mathbf{y}) \\ + \alpha \beta \gamma^2 (\alpha - \beta) D_{y_2} \tau(l, m, n + 1; \mathbf{y}) \cdot \tau(l + 1, m + 1, n; \mathbf{y}) \\ = \beta \gamma (\beta - \gamma) D_{y_0} \tau(l + 1, m, n; \mathbf{y}) \cdot \tau(l, m + 1, n + 1; \mathbf{y}) \\ + \gamma \alpha (\gamma - \alpha) D_{y_0} \tau(l, m + 1, n; \mathbf{y}) \cdot \tau(l + 1, m, n + 1; \mathbf{y}) \\ + \alpha \beta (\alpha - \beta) D_{y_0} \tau(l, m, n + 1; \mathbf{y}) \cdot \tau(l + 1, m + 1, n; \mathbf{y}) \\ - (\alpha - \beta)(\beta - \gamma)(\gamma - \alpha) \\ \times D_{y_0} \tau(l, m, n; \mathbf{y}) \cdot \tau(l + 1, m + 1, n + 1; \mathbf{y}). \end{aligned} \tag{15}$$

We further impose the condition  $\beta = \gamma$ . Then the  $\tau$ -function  $\tau(l, m, n; \mathbf{y})$  depends only on  $k \stackrel{\text{def}}{=} m - n, l$  and  $\mathbf{y}$ . In this sense, we rewrite

$$\tau(l, m, n; \mathbf{y}) \rightarrow \tau(l, k; \mathbf{y}).$$



**Figure 1.** Special case of a two-soliton solution ('V-soliton') with  $p_1 = p_2$  ( $p_1 = p_2 = 0.3$ ,  $r_1 = 0.15$ ,  $r_2 = -0.1$ ,  $a_1 = a_2 = 1$ ,  $\alpha = 0.8$ ,  $\beta = 0.5$ ).

Under this condition, (14) and (15) are reduced to

$$2\alpha \tau(l+1, k; \mathbf{y})\tau(l, k; \mathbf{y}) - (\alpha + \beta) \tau(l, k+1; \mathbf{y})\tau(l+1, k-1; \mathbf{y}) - (\alpha - \beta) \tau(l, k-1; \mathbf{y})\tau(l+1, k+1; \mathbf{y}) = 0 \quad (16)$$

$$\begin{aligned} \alpha\beta^2 D_{y_2}(2\alpha \tau(l+1, k; \mathbf{y}) \cdot \tau(l, k; \mathbf{y}) - (\alpha + \beta) \tau(l, k+1; \mathbf{y}) \cdot \tau(l+1, k-1; \mathbf{y}) \\ - (\alpha - \beta) \tau(l, k-1; \mathbf{y}) \cdot \tau(l+1, k+1; \mathbf{y})) \\ = D_{y_0}(2(2\beta^2 - \alpha^2) \tau(l+1, k; \mathbf{y}) \cdot \tau(l, k; \mathbf{y}) \\ - \alpha(\alpha + \beta) \tau(l, k+1; \mathbf{y}) \cdot \tau(l+1, k-1; \mathbf{y}) \\ - \alpha(\alpha - \beta) \tau(l, k-1; \mathbf{y}) \cdot \tau(l+1, k+1; \mathbf{y})). \end{aligned} \quad (17)$$

Furthermore, we can construct the  $N$ -soliton solution by applying (13) to (12)

$$\begin{aligned} \tau_N(l, k; y_0, y_2) = \sum_{l=0}^N \sum_{j_1 < \dots < j_l} c_{j_1 \dots j_l} \prod_{m=1}^l \phi_{j_m}(l, k; y_0, y_2) \\ \phi_j(l, k; y_0, y_2) \stackrel{\text{def}}{=} a_j \exp(r_j y_0 + r_j p_j^2 y_2) \left( \frac{1 + p_j \alpha}{1 - p_j \alpha} \right)^l \left( \frac{1 + p_j \beta}{1 - p_j \beta} \right)^k \end{aligned} \quad (18)$$

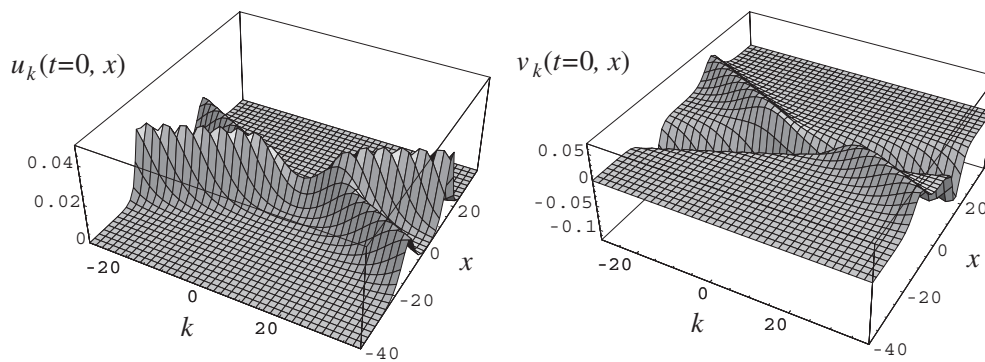
where  $c_{j_1 \dots j_l}$  is the same as the continuum one (12). We remark that the  $N$ -soliton  $\tau$ -function can be written as the Wronskian determinant. Using the determinant expression, we can show that both (16) and (17) are reduced to the Plücker relations.

Introducing the variables as

$$\begin{aligned} \partial_t \stackrel{\text{def}}{=} \frac{2}{\alpha^2} \partial_{y_0} - 2\partial_{y_2} \quad \partial_x \stackrel{\text{def}}{=} \partial_{y_2} - \frac{1}{\beta^2} \partial_{y_0} \\ u_k(t, x) \stackrel{\text{def}}{=} \log \left[ \left( \frac{\beta - \alpha}{\beta + \alpha} \right)^{1/2} \frac{\tau(l+1, k+1)\tau(l, k)}{\tau(l, k+1)\tau(l+1, k)} \right] \\ v_k(t, x) \stackrel{\text{def}}{=} \partial_x \log \frac{\tau(l, k+2)}{\tau(l, k)} \end{aligned}$$

we have the differential–difference equations (4) and (5), which have a  $N$ -soliton solution corresponding to the  $\tau$ -function (18).

Let us consider the behaviour of  $u_k(t, x)$  and  $v_k(t, x)$  corresponds to (18) with  $N = 2$  (two-soliton solution). The choice  $p_1 = p_2$  gives a travelling wave solution that has a 'V' shape (figure 1). In generic cases ( $p_1 \neq p_2$ ) the solution has the same features as the two-soliton solution of the KP equation (figure 2).



**Figure 2.** Two-soliton solution with  $p_1 \neq p_2$  ( $p_1 = 0.3$ ,  $p_2 = 0.23$ ,  $r_1 = 0.15$ ,  $r_2 = -0.1$ ,  $a_1 = a_2 = 1$ ,  $\alpha = 0.8$ ,  $\beta = 0.5$ ).

#### 4. Concluding remarks

In this paper, we have introduced the differential–difference system (4) and (5), which is related to the toroidal Lie algebra,  $\mathfrak{sl}_2^{\text{tor}}$ . Since the symmetry of the toroidal Lie algebra allows us to introduce extra parameters of wavenumbers in the soliton solution (i.e.  $r_j$  in (12) and (18)), it might be possible to construct some interesting solutions. In particular, we can obtain a class of travelling-wave solutions that are ‘V’ shaped (figure 1), which is a special case of two-soliton solutions. The existence of the V-soliton type solution is one of the features of this class of equations.

We note that there exist solutions of the same shape for the  $(2 + 1)$ -dimensional KdV equation (1), and for a  $(2 + 1)$ -dimensional generalization of the nonlinear Schrödinger (NLS) equation [15] that also has the symmetry of toroidal Lie algebra  $\mathfrak{sl}_2^{\text{tor}}$  [17]. We also remark that Oikawa *et al* [16] discussed the propagation of the V-soliton in a two-layer fluid, which is governed by an equation similar to the  $(2 + 1)$ -dimensional NLS equation.

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